



Optimisation of CB sensing

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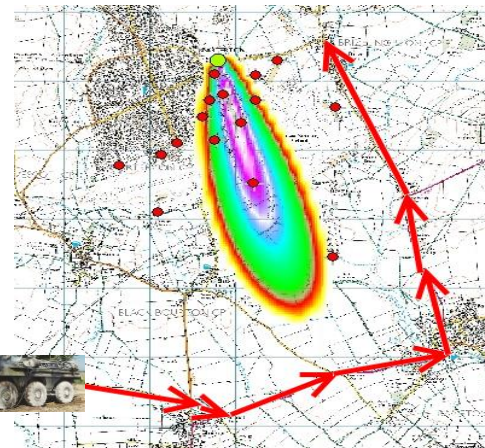
UK OFFICIAL



Ministry
of Defence

- Motivation
 - Hazard identification and characterisation
- Background
 - Decision Support Tools
- Background
 - Sensor Placement Tool (SPT)
- Latest SPT developments
 - Correlation
- Future focus
 - Complex sensor systems

- To **reduce casualties** and **maintain tempo** during a CBR event it is necessary to **understand** the **downwind hazard**
- Immediate impacts
 - **Masking/de-masking** strategies
 - Minimise casualties
 - Alternative courses of action
 - Hazard **avoidance**
 - Minimize protection requirement
- Medium-term response
 - **Decontamination** (from deposition)
 - Personnel
 - Assets
 - Medical **countermeasures**
 - Minimise use
- Long-term response
 - **Forensics**
 - Examination of release location





- **Decision support tools** have wide-ranging application to support the **military** commander

- **Strategic** through to **tactical** command levels

- Pre-deployment planning

- In support of **acquisition** programmes

- Deployment / pre-event

- What should be **deployed** and where?

- During / post-event

- **Mitigation** strategies

- Consequence **management**

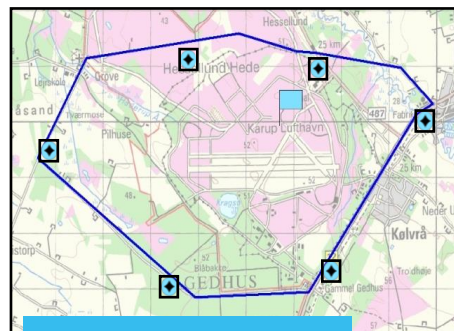
- Maintain operational **tempo**

- Two key capabilities

- **Sensor Placement Tool**
- **Source Term Estimation**



Source Term
Estimation



Sensor Placement



Estimated
location

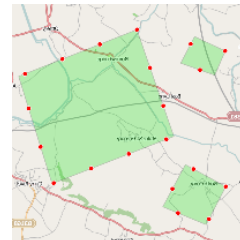
- UK MOD requires **expert advice** to ensure **optimum benefit** from and **cost effectiveness** of the **CB sense** capability
- This **advice** is supplied through the Sensor Placement Tool (**SPT**) which has two main uses:
 - To support **procurement** of sensor technologies by assessing and scoring various configurations of sensors
 - As a planning capability **identifying optimal locations** in which to place sensors



Dice-5



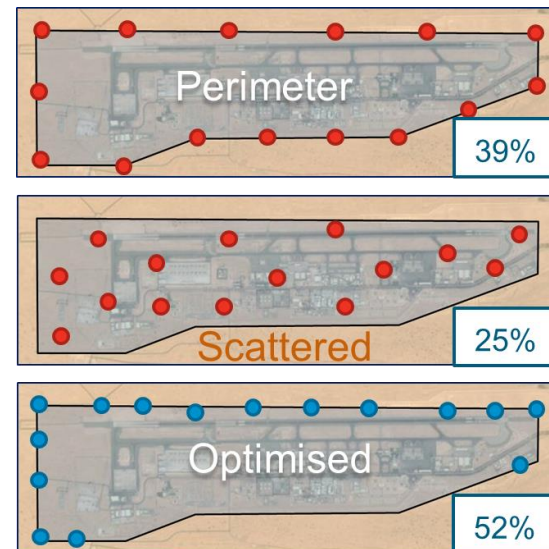
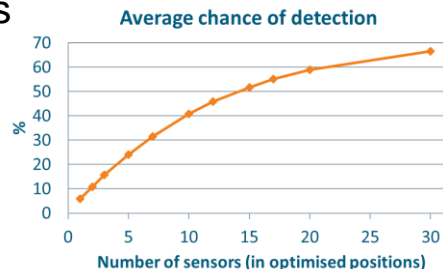
Perimeter



Picket fence



- Sense system **performance** depends on numerous factors:
 - **Meteorology** / **Threat** details / Quality and quantity of **sensors**
- Sensor Placement Tool
 - **Assesses** sensor systems
 - Provides analysis of **protection** levels
 - Optimises sensor **placement**
- SPT has been used to:
 - **Identify** what is achievable
 - Inform **requirements**
 - **Down-select** system concepts
 - Generate **laydowns** for Bio sense capability **operationally**

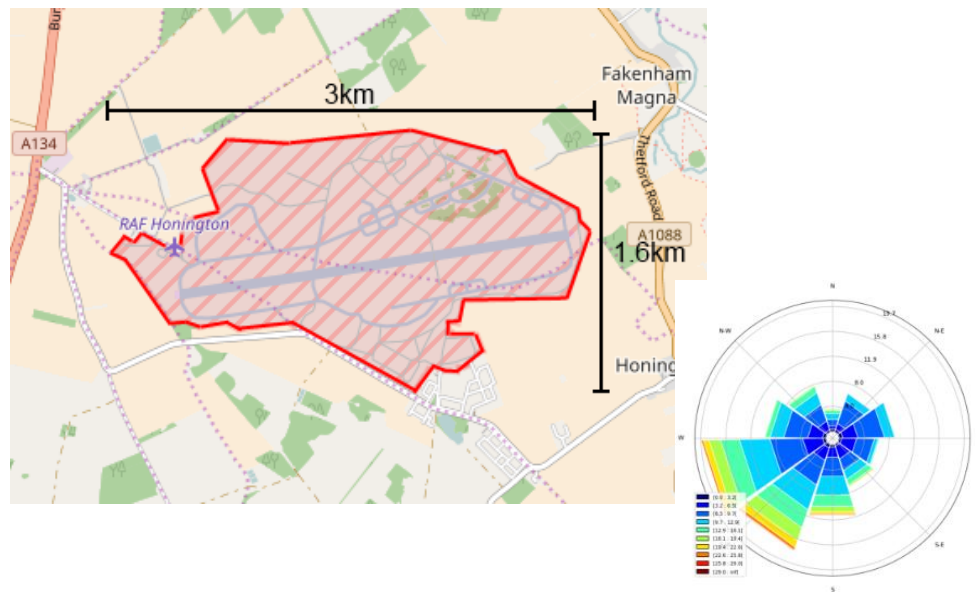


- **Fitness function** designed to assess a given sensor placement based on criteria of interest:
 - Probability of **detection**
 - Probability of **one or more sensors** detecting a threat over the length of the simulation
 - Warning time
 - Specify a desired **warning time** and assess ability of a group of sensors to alarm in a **timely** manner
 - **Desirability**
 - Allows algorithm to assign preferential **weights** to areas where sensor placement is more convenient or **exclude** / **penalise** areas where sensors can't be placed (e.g. runways)
- Optimisation algorithm run to find best fitness value
 - Modified **simulated annealing** approach
 - Set a maximum number of iterations (typically 1×10^6)
 - Modifications to avoid getting stuck at local extrema

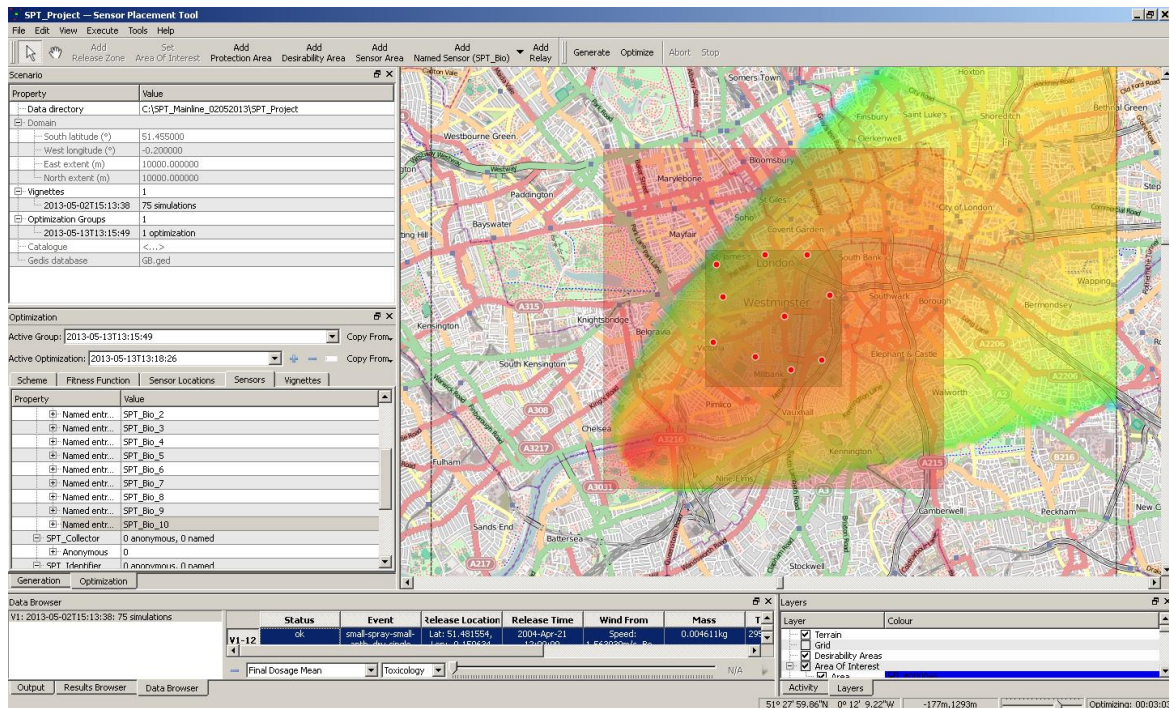
Overview: Provide a sensor placement laydown for RAF Honington to support a Biological Surveillance Collector System (BSCS) user field trial

Information we require:

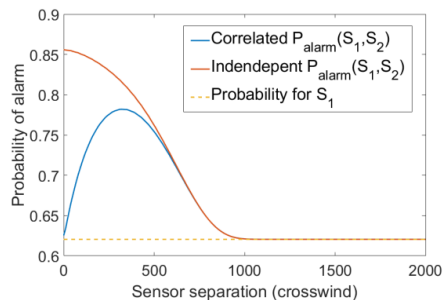
- **Base Location:**
 - 52.335N, -0.7754W
- **Base Dimension:**
 - See map
- **Threat Type:**
 - **Biological** sprayer
 - **Off-base releases** up to 2 km away
- **Meteorology:**
 - **Historical** (current month)
- **Sensor Type:**
 - Up to **15 BW collectors**
 - Collectors must be placed **on-base**
 - Avoid placing collectors on the runway



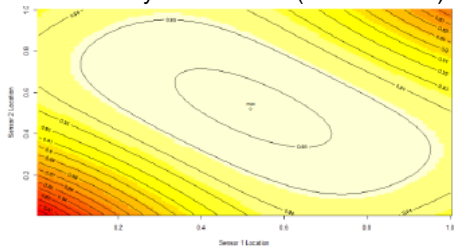
Where Do I Place My Sensors?



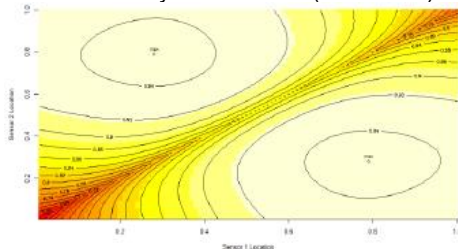
Optimized Sensor Placement provided through the **Sensor Placement Tool**



Probability of Detection (uncorrelated)



Probability of Detection (correlated)

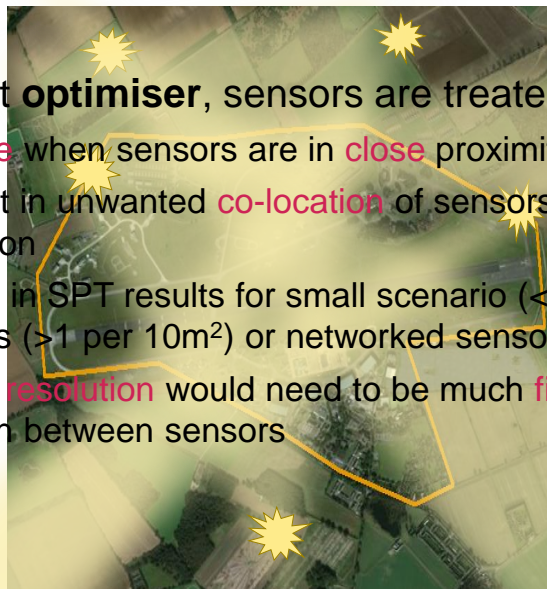


1. SPT **threats** are generated first and stored as **data grids** for **multiple time points**

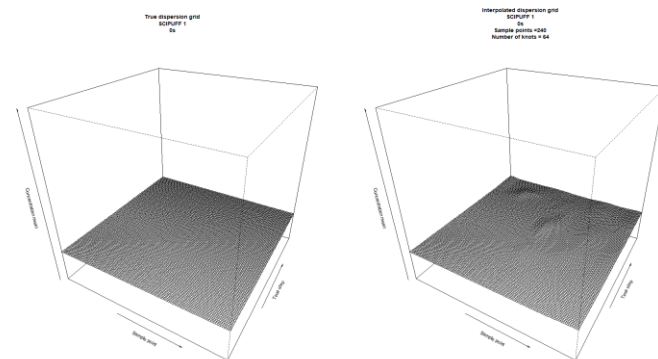
- 1 minute temporal resolution; 6 hour periods
- Large amounts of data (~20Gb)

2. In the current **optimiser**, sensors are treated **independently**

- **Inaccurate** when sensors are in **close** proximity
- Can result in unwanted **co-location** of sensors from sensor optimization
- Limitation in SPT results for small scenario (<1 km²), large number of sensors (>1 per 10m²) or networked sensors
- Temporal **resolution** would need to be much **finer** to incorporate correlation between sensors

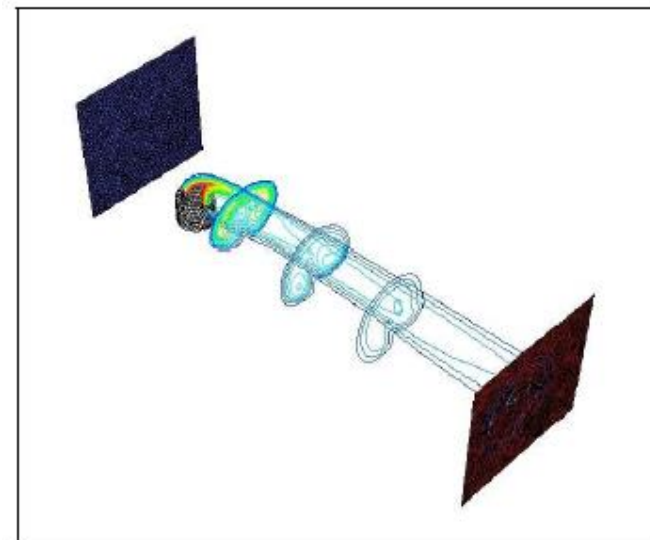


- Initial investigation into **correlation algorithm** identified opportunity in **rapid** dispersion modelling
 - Dispersion model **emulation**
 - Data compression
 - Threat data storage not required
- Fundamental change to SPT approach
 - Enabler for **moving sensor** capability
 - Expands **deployment** potential



Work to-date has included:

- Use of **Gaussian processes** to estimate spatio-temporal correlations for large number of sensors
- Development a **testbed** which includes:
 - Efficient method of calculating probability of alarm, with **pair-wise correlation** between sensors
 - Algorithms designed to **reduce memory usage** during optimisation phase
- Validation studies for correlation algorithms
 - CFD simulations using **ANSYS Fluent**
 - Analysis of existing **wind tunnel data** from Dstl

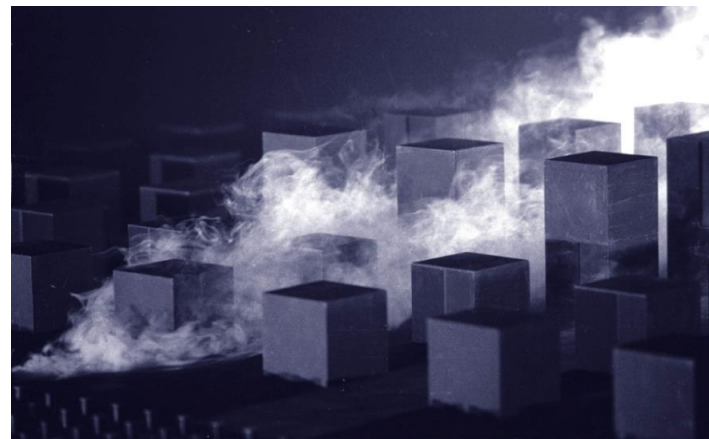


Fluent simulation of smoke from a chimney



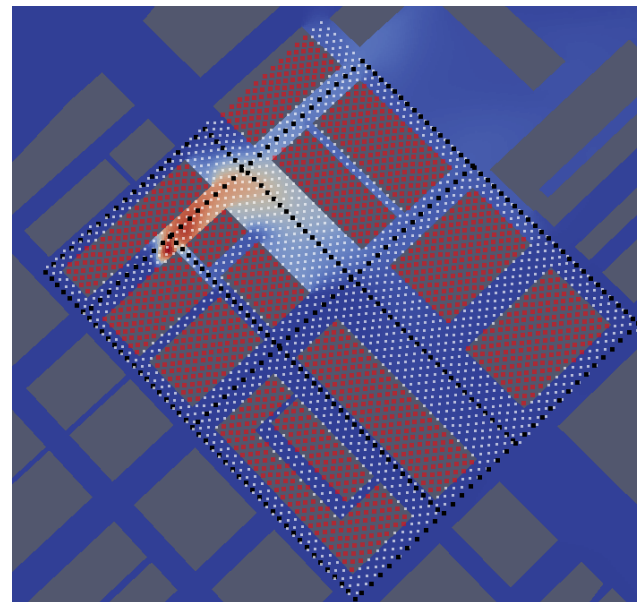
Ongoing work:

- Integrating the **data compression algorithm** into the testbed to remove dependence on the **grid** and reduce storage required
- Testing of **different** optimisation algorithms within the testbed
- Further **validation** studies using **wind tunnel data** to determine correlation between real sensors



Credit: I. Hall

- Development of an SPT-type **framework** that operates across a **continuous** parameter space
- Application to **complex** sensor systems
 - Optimisation of the **path** of **moving** sensors
 - Assessment / optimisation of **networked** sensor systems
- Optimisation for **source-term estimation**
- Deployment and real-time operation on **hand-held devices**



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